Lorentz Force $\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$

- Electric force can accelerate objects by changing their speed and/or direction.
- Electric force can do work, $W_E = \int q \vec{E} \cdot d\vec{s}$
- Magnetic force can only accelerate objects by changing their direction. (Acts perpendicular to velocity.)
- Magnetic force does not do work,

$$W_B = \int (q\vec{v} \times \vec{B}) \cdot \vec{v}dt = 0$$
 (where $\vec{v} = \frac{d\vec{s}}{dt}$)

Magnetic Forces on Currents

Consider charges moving in a wire in a magnetic field.





Magnetic Forces on Currents

Consider charges moving in a wire in a magnetic field. \vec{F}



\vec{F}	_	$q\vec{v}$	X	\vec{B}



Magnetic Forces on Currents Curved wires

 $\vec{F} = \int d\vec{F}$ $\vec{F} = I \int d\vec{s} \times \vec{B}$



Example: A section of current-carrying wire is in a uniform magnetic field, as illustrated. Determine the net force on the wire.



Example: A section of current-carrying wire is in a uniform magnetic field, as illustrated. Determine the net force on the wire.



Example: A quarter of a circular loop of current-carrying wire is in a uniform magnetic field, as illustrated. Determine the net force on the wire.



Magnetic Forces on Current Loops Rectangular Loops



Magnetic Forces on Current Loops Rectangular Loops







Approximate loop by set of rectangular loops.



Approximate loop by set of rectangular loops. Interior sections cancel.



Approximate loop by set of rectangular loops. Interior sections cancel. $\vec{F}_{Total} = 0$



Approximate loop by set of rectangular loops. Interior sections cancel. $\vec{F}_{Total} = 0$

Magnetic Torques on Current Loops Rectangular Loops



Magnetic Torques on Current Loops Rectangular Loops

 $\vec{\tau} = \vec{r} \times \vec{F}$





Magnetic Dipole Moment

 $\vec{\tau} = I\vec{A} \times \vec{B}$

Can be written as

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$

Where

 $\vec{\mu} = NI\vec{A}$

(*N* is the number of wire loops.)

Magnetic Dipole Moment

 $\vec{\mu} = NI\vec{A}$

Torque:

Energy:

\rightarrow \rightarrow	\rightarrow
$\vec{\tau} = \vec{u} \vee D$	$II - \vec{u} \cdot D$
$\iota - \iota \land D$	$Uu \cdot D$

Magnetic Dipole Moment

 $\vec{\mu} = NI\vec{A}$

Torque:	Energy:
$\vec{\tau} = \vec{\mu} \times \vec{B}$	$U = -\vec{\mu} \cdot \vec{B}$

Recall electric dipoles.

$$\vec{\tau} = \vec{p} \times \vec{E}$$
 $U = -\vec{p} \cdot \vec{E}$

Example: A magnetic dipole is in a uniform magnetic field. Under what conditions is (a) the torque a minimum, (b) the torque zero, (c) the potential energy a minimum, (d) the potential energy zero?

$$\vec{\mu} = NI\vec{A}$$

Torque:

Energy:

<u> </u>	\rightarrow		\rightarrow
$\vec{\tau} = $	$\vec{\mu} \times B$	U = -	- <i>ū</i> • B

Galvanometer



What causes the forces on the needle?

Hyperphysics has nice interactive graphics showing how <u>dc</u> and <u>ac</u> motors work.



