


### Magnetism

**Magnetic "charges"**

- Called poles
- Two types, North and South
- Like poles repel each other
- Opposite poles attract each other
- Found only in North/South pairs (Dipoles)

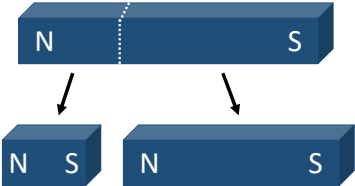


### Magnetism

**Magnetic poles**

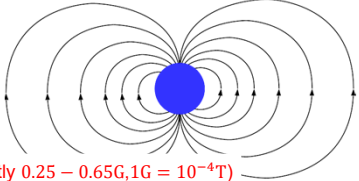
- Found only in North/South pairs

Cutting a magnet in two will not isolate the poles.  
Cutting a magnet in two produces two magnets.



### Earth as a Magnet

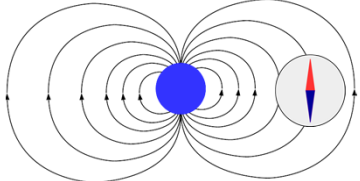
The strength and orientation of the earth's magnetic field varies over time and location.



(Currently  $0.25 - 0.65 \text{G}$ ,  $1\text{G} = 10^{-4}\text{T}$ )  
The earth's magnetic poles are "near" the geographic poles (where the axis of rotation intersects the earth's surface).

### Earth as a Magnet

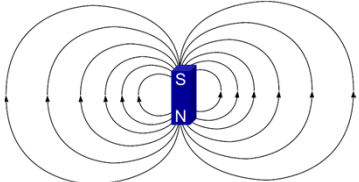
North Pole of compass points towards Geographic North Pole. Opposites attract.



Geographic North Pole is (near) Magnetic South Pole and Geographic South Pole is (near) Magnetic North Pole.

### Magnetic Field Lines

Originate at North Poles  
Terminate at South Poles



### Magnetic Forces

Magnetic fields can produce forces

$$\vec{F} = q\vec{v} \times \vec{B}$$

- No forces on particles at rest
- No forces on particles moving parallel to field
- Force is perpendicular to field
- Force is perpendicular to particle's velocity

Cross Product Review

$\vec{A} \times \vec{B}$

Magnitude of cross product is the product of perpendicular components.

$|\vec{A} \times \vec{B}| = AB \sin \theta$

where  $\theta$  is the angle between  $\vec{A}$  and  $\vec{B}$ .

Cross Product Review

$\vec{A} \times \vec{B}$

Direction of cross product is the direction perpendicular to both  $\vec{A}$  and  $\vec{B}$  with the ambiguity removed by application of the "Right Hand Rule".

Cross Product Review  
Right Hand Rule

Point 1<sup>st</sup> finger in direction of  $\vec{A}$ .  
Point 2<sup>nd</sup> finger in direction of  $\vec{B}$ .  
Cross product is in direction of thumb.

Examples: Determine the direction of the force for each combination of charge, velocity and magnetic field.

Proton 	Proton 
Electron 	Proton 

Example: Determine the force acting on a proton moving with speed  $v_0 = 200\text{m/s}$  at an angle of  $30^\circ$  relative to a magnetic field,  $B = 0.04\text{T}$ .

Example: Determine the force acting on an electron moving with speed  $v_0 = 200\text{m/s}$  at an angle of  $30^\circ$  relative to a magnetic field,  $B = 0.04\text{T}$ .

Cross Product Review  
Multiplying Components

$$\vec{A} \times \vec{B} = \begin{vmatrix} A_x & A_y & A_z \\ B_x & B_y & B_z \\ \hat{i} & \hat{j} & \hat{k} \end{vmatrix}$$

$$= (A_y B_z - A_z B_y)\hat{i} + (A_z B_x - A_x B_z)\hat{j} + (A_x B_y - A_y B_x)\hat{k}$$

Cross Product Review  
Multiplying Components

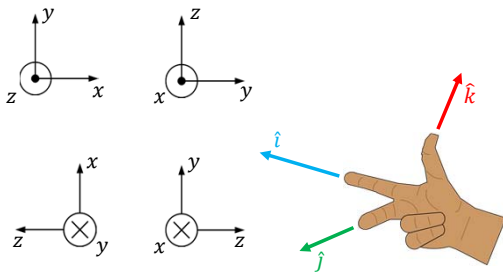
$$\vec{A} \times \vec{B} = \begin{vmatrix} A_x & A_y & A_z \\ B_x & B_y & B_z \\ \hat{i} & \hat{j} & \hat{k} \end{vmatrix}$$

$$= (A_y B_z - A_z B_y)\hat{i} + (A_z B_x - A_x B_z)\hat{j} + (A_x B_y - A_y B_x)\hat{k}$$

Note that  $\hat{i} \times \hat{j} = \hat{k}$      $\hat{j} \times \hat{k} = \hat{i}$      $\hat{k} \times \hat{i} = \hat{j}$   
 $\hat{j} \times \hat{i} = -\hat{k}$      $\hat{k} \times \hat{j} = -\hat{i}$      $\hat{i} \times \hat{k} = -\hat{j}$

Cross Product Review

All versions of determining the cross product assume a right-handed coordinate system.

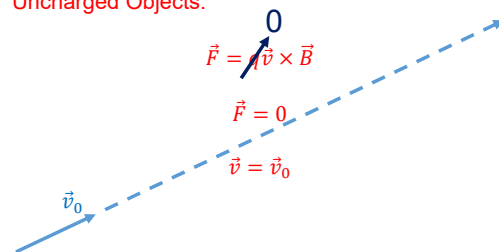


Example: An object with charge,  $q = 5C$ , is moving with initial velocity,  $\vec{v}_0 = 2(m/s)\hat{i} - 3(m/s)\hat{j}$ , in a region with a uniform magnetic field,  $\vec{B} = -4T\hat{i} + 4T\hat{j} + 5T\hat{k}$ . Determine the initial force on the object.

Example: An electron entering a region of uniform magnetic field,  $\vec{B} = 0.50T\hat{j}$ , experiences a force,  $\vec{F} = 3.28 \times 10^{-13}N\hat{k}$ . Determine the initial velocity of the electron.

Motion in a Magnetic Field

Uncharged Objects:



Motion of Charged Object in a Uniform Magnetic Field

Initially moving parallel to field:

$\vec{F} = q\vec{v} \times \vec{B}$   
 $\vec{F} = 0$   
 $\vec{v} = \vec{v}_0$

Continues to move parallel to field.

Motion of Charged Object in a Uniform Magnetic Field

Initially moving perpendicular to field:

$\vec{F} = q\vec{v} \times \vec{B}$

Circular motion:

Motion of Charged Object in a Uniform Magnetic Field

Initially moving perpendicular to field:

$\vec{F} = q\vec{v} \times \vec{B}$   
 Force,  $F_r = -|q|vB$

Circular motion:

$F_r = -\frac{mv_t^2}{r}$

Motion of Charged Object in a Uniform Magnetic Field

Initially moving perpendicular to field:

$\vec{F} = q\vec{v} \times \vec{B}$   
 Force,  $F_r = -|q|vB$

Circular motion:

$F_r = -\frac{mv_t^2}{r}$   
 $-|q|v_0B = -\frac{mv_0^2}{r}$   
 $r = \frac{mv_0}{|q|B}$

Motion of Charged Object in a Uniform Magnetic Field

Initially moving perpendicular to field:

Force,  $F_r = -|q|vB$   
 Radius,  $r = \frac{mv_0}{|q|B}$

Period:

$T = \frac{2\pi r}{v} = \frac{2\pi r}{\left(\frac{|q|Br}{m}\right)}$   
 $T = \frac{2\pi m}{|q|B}$

Motion of Charged Object in a Uniform Magnetic Field

Initially moving perpendicular to field:

Force,  $F_r = -|q|vB$   
 Radius,  $r = \frac{mv_0}{|q|B}$   
 Period,  $T = \frac{2\pi m}{|q|B}$

Frequency:

$f = \frac{1}{T} = \frac{|q|B}{2\pi m}$

Motion of Charged Object in a Uniform Magnetic Field

Motion neither parallel nor perpendicular to field:

Motion of Charged Object in a Uniform Magnetic Field

Motion neither parallel nor perpendicular to field:

Velocity broken into two components  
Parallel to  $\vec{B}$   
Perpendicular to  $\vec{B}$

Motion of Charged Object in a Uniform Magnetic Field

Motion neither parallel nor perpendicular to field:

Parallel component yields straight line path

Perpendicular component yields circular path.

Motion of Charged Object in a Uniform Magnetic Field

Motion neither parallel nor perpendicular to field:

Result is helical motion, centered on axis parallel to  $\vec{B}$ .

Motion in Electric and Magnetic Fields  
Lorentz Force

Combining  $\vec{F} = q\vec{E}$  and  $\vec{F} = q\vec{v} \times \vec{B}$

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$$

Some conditions result in simple motion:

- Uniform  $\vec{E}$  with  $\vec{B} = 0$
- Uniform  $\vec{B}$  with  $\vec{E} = 0$
- $\vec{E} \perp \vec{v}_0$ ,  $\vec{B} \perp \vec{v}_0$  and  $\vec{B} \perp \vec{E}$  (Crossed fields)

Crossed Fields  
Velocity Selector

### Crossed Fields Velocity Selector

$$\left. \begin{aligned} \vec{v} &= v_0 \hat{i} \\ \vec{E} &= E \hat{j} \\ \vec{B} &= B \hat{k} \end{aligned} \right\} \begin{aligned} \vec{F} &= q(E \hat{j} + v_0 \hat{i} \times B \hat{k}) \\ \vec{F} &= q(E - v_0 B) \hat{j} \end{aligned}$$

### Crossed Fields Velocity Selector

$$\left. \begin{aligned} \vec{v} &= v_0 \hat{i} \\ \vec{E} &= E \hat{j} \\ \vec{B} &= B \hat{k} \end{aligned} \right\} \begin{aligned} \vec{F} &= q(E \hat{j} + v_0 \hat{i} \times B \hat{k}) \\ \vec{F} &= q(E - v_0 B) \hat{j} \end{aligned}$$

If  $v_0 = \frac{E}{B}$ , then  $\vec{F} = 0$  and the trajectory is a straight line.

### Mass Spectrometer

Charge accelerates between plates, gaining energy,  $\Delta U = q\Delta V$ .

Velocity is function of  $\Delta V$ .

$$\frac{1}{2}mv^2 = q\Delta V$$

$$v = \sqrt{\frac{2q\Delta V}{m}}$$

### Mass Spectrometer

Charge moves in circular path in spectrometer.

Radius of path is function of mass.

$$qvB = \frac{mv^2}{r}$$

$$r = \frac{mv}{qB}$$

### Mass Spectrometer

Combining

$$v = \sqrt{\frac{2q\Delta V}{m}} \quad \& \quad r = \frac{mv}{qB}$$

yields

$$r = \frac{1}{B} \sqrt{\frac{2m\Delta V}{q}}$$

Radius is a function of mass/charge ratio.

### Magnetic Flux

“Counting field lines” through a surface

$$\Phi_B = \int \vec{B} \cdot d\vec{A}$$

- Area vector
- Magnitude of area
- Direction normal (perpendicular) to surface

## Gauss's Law for Magnetism

$$\Phi_B = \oint \vec{B} \cdot d\vec{A} \sim q_{B,\text{enclosed}}$$

- $q_B$  refers to magnetic charge.
- Magnetic charges are called poles (North/South) and come in pairs with net magnetic charge of 0.
- A single magnetic charge is called a monopole. No monopole has ever been observed.

$$\Phi_B = \oint \vec{B} \cdot d\vec{A} = 0$$

## Gauss's Law for Magnetism

$$\Phi_B = \oint \vec{B} \cdot d\vec{A} = 0$$

- There are no magnetic monopoles.
- All magnetic field lines entering a closed surface also exit the closed surface.

Magnetic flux through an open surface will be of more importance in this course than total flux through a closed surface.

$$\Phi_B = \int \vec{B} \cdot d\vec{A}$$