

# Partial Averaging of Fuzzy Differential Equations with Maxima

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## Abstract

In this paper, a scheme of partial averaging of fuzzy differential equations with maxima is considered.

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## 1 Introduction

The study of fuzzy differential equations (FDEs) forms a suitable setting for the mathematical modelling of real world problems in which uncertainty or vagueness pervades. Fuzzy differential equations were first formulated by Kaleva [4, 5]. He used the concept of H-differentiability which was introduced by Puri and Ralescu [13], and obtained the existence and uniqueness theorem for a solution of FDE under the Lipschitz condition. Since then there appeared a lot of papers concerning the theory and applications of fuzzy differential equations, fuzzy dynamics and fuzzy differential inclusions [2, 9, 10, 12].

In this paper, a scheme of partial averaging of fuzzy differential equations with maxima is considered that continues researches devoted to the fuzzy differential equations with delay [7, 8].

## 2 Main Definitions

Let  $\text{conv}(\mathbb{R}^n)$  be a family of all nonempty compact convex subsets of  $\mathbb{R}^n$  with Hausdorff metric

$$h(A, B) = \max\left\{\max_{a \in A} \min_{b \in B} \|a - b\|, \max_{b \in B} \min_{a \in A} \|a - b\|\right\},$$

where  $\|\cdot\|$  denotes the usual Euclidean norm in  $\mathbb{R}^n$ . Denote by  $|A| = h(A, 0)$ .

Let  $E^n$  be a family of mappings  $x : \mathbb{R}^n \rightarrow [0, 1]$  satisfying the following conditions:

- 1)  $x$  is normal, i.e., there exists  $y_0 \in \mathbb{R}^n$  such that  $x(y_0) = 1$ ;
- 2)  $x$  is fuzzy convex, i.e.,  $x(\lambda y + (1 - \lambda)z) \geq \min\{x(y), x(z)\}$  whenever  $y, z \in \mathbb{R}^n$  and  $\lambda \in [0, 1]$ ;
- 3)  $x$  is upper semicontinuous, i.e., for any  $y_0 \in \mathbb{R}^n$  and  $\varepsilon > 0$  there exists  $\delta(y_0, \varepsilon) > 0$  such that  $x(y) < x(y_0) + \varepsilon$  whenever  $\|y - y_0\| < \delta$ ,  $y \in \mathbb{R}^n$ ;
- 4) the closure of the set  $\{y \in \mathbb{R}^n : x(y) > 0\}$  is compact.

Let  $\widehat{0}$  be a fuzzy mapping defined by  $\widehat{0}(y) = \begin{cases} 0 & \text{if } y \neq 0, \\ 1 & \text{if } y = 0. \end{cases}$

**Definition 2.1** (See [11]). The set  $\{y \in \mathbb{R}^n : x(y) \geq \alpha\}$  is called an  $\alpha$ -level  $[x]^\alpha$  of a mapping  $x \in E^n$  for  $\alpha \in (0, 1]$ . A closure of the set  $\{y \in \mathbb{R}^n : x(y) > 0\}$  is called a 0-level  $[x]^0$  of a mapping  $x \in E^n$ .

Define the metric  $D : E^n \times E^n \rightarrow \mathbb{R}_+$  by the equation

$$D(x, y) = \sup_{\alpha \in [0, 1]} h([x]^\alpha, [y]^\alpha).$$

Let  $I$  be an interval in  $\mathbb{R}$ .

**Definition 2.2.** A mapping  $f : I \rightarrow E^n$  is called weakly continuous at point  $t_0 \in I$  if a multivalued mapping  $f_\alpha(t) = [f(t)]^\alpha$  is continuous for any  $\alpha \in [0, 1]$ .

**Definition 2.3** (See [11]). A mapping  $f : I \times E^n \rightarrow E^n$  is called weakly continuous at point  $(t_0, x_0) \in I \times E^n$  if for any  $\alpha \in [0, 1]$  and  $\varepsilon > 0$  there exists  $\delta(\varepsilon, \alpha) > 0$  such that  $h(f_\alpha(t, x), f_\alpha(t_0, x_0)) < \varepsilon$  for all  $(t, x) \in I \times E^n$  satisfying the condition  $|t - t_0| < \delta(\varepsilon, \alpha)$ ,  $h([x]^\alpha, [x_0]^\alpha) < \delta(\varepsilon, \alpha)$ .

**Definition 2.4** (See [11]). A mapping  $f : I \rightarrow E^n$  is called measurable on  $I$  if a multivalued mapping  $f_\alpha(t)$  is Lebesgue measurable for any  $\alpha \in [0, 1]$ .

**Definition 2.5** (See [11]). An element  $g \in E^n$  is called an integral of  $f : I \rightarrow E^n$  over  $I$  if  $[g]^\alpha = (A) \int_I f_\alpha(t) dt$  for any  $\alpha \in (0, 1]$ , where  $(A) \int_I f_\alpha(t) dt$  is the Aumann integral [1].

**Definition 2.6** (See [11]). A mapping  $f : I \rightarrow E^n$  is called differentiable at point  $t_0 \in I$  if the multivalued mapping  $f_\alpha(t)$  is Hukuhara differentiable at point  $t_0$  [3] for any  $\alpha \in [0, 1]$  and the family  $\{D_H f_\alpha(t_0) : \alpha \in [0, 1]\}$  defines a fuzzy number  $f'(t_0) \in E^n$  (which is called a fuzzy derivative of  $f(t_0)$  at point  $t_0$ ).

Consider a fuzzy differential equation with delay

$$x'(t) = f(t, x(t), x(\alpha(t))), \quad x(t_0) = x_0, \tag{2.1}$$

where  $t \in I$  is time;  $x \in S \subset E^n$  is a phase variable; the initial conditions  $t_0 \in I, x_0 \in S$ ; a fuzzy mapping  $f : I \times S \times S \rightarrow E^n$ ; a delay function  $\alpha(t) \in [t_0, t]$ .

**Definition 2.7.** A fuzzy mapping  $x : I_0 \rightarrow E^n, t_0 \in I_0 \subset I$ , is called a solution of equation (2.1) if it is weakly continuous and for all  $t \in I_0$  satisfies the integral equation

$$x(t) = x_0 + \int_{t_0}^t f(s, x(s), x(\alpha(s)))ds.$$

**Theorem 2.8** (See [8]). *Let  $f(t, x, y)$  be a weakly continuous function in the neighborhood of the point  $(t_0, x_0, x_0)$  and satisfy the Lipschitz condition in  $x, y$  with constant  $\lambda$ . Then there exists a unique solution  $x(t)$  of equation (2.1) for  $t \in [t_0, t_0 + \sigma]$ , where  $\sigma$  is small enough.*

### 3 Main Results

Consider the fuzzy differential equation with maxima

$$x'(t) = \varepsilon f \left( t, x(t), \max_{\tau \in [\gamma(t), g(t)]} |x(\tau)| \right), \quad x(0) = x_0, \tag{3.1}$$

where  $t \geq 0$  is time;  $x \in S \subset E^n$  is a phase variable;  $\varepsilon > 0$  is a small parameter; the initial condition  $x_0 \in S$ ; a fuzzy mapping  $f : \mathbb{R}_+ \times S \times \mathbb{R}_+ \rightarrow E^n$ ; the functions  $0 \leq \gamma(t) \leq g(t) \leq t$ .

If there exists a fuzzy mapping  $\bar{f}(t, x, z)$  such that for any  $t, z \geq 0, x \in S \subset E^n$

$$\lim_{T \rightarrow \infty} \frac{1}{T} D \left( \int_t^{t+T} f(s, x, z)ds, \int_t^{t+T} \bar{f}(s, x, z)ds \right) = 0, \tag{3.2}$$

then in the correspondence to equation (3.1) we will set the following partially averaged equation

$$y'(t) = \varepsilon \bar{f} \left( t, y(t), \max_{\tau \in [\gamma(t), g(t)]} |y(\tau)| \right), \quad y(0) = x_0. \tag{3.3}$$

**Theorem 3.1.** *Let in the domain  $Q = \{t, z \geq 0, x \in S \subset E^n\}$  the following hold:*

1. *the fuzzy mappings  $f(t, x, z), \bar{f}(t, x, z)$  are uniformly bounded by  $M$ , weakly continuous in  $t$  and satisfy the Lipschitz condition in  $x, z$  with constant  $\lambda$ , i.e.,*

$$\begin{aligned} D(f(t, x, z), \widehat{0}) &\leq M, \quad D(\bar{f}(t, x, z), \widehat{0}) \leq M, \\ D(f(t, x, z), f(t, x', z')) &\leq \lambda [D(x, x') + |z - z'|], \\ D(\bar{f}(t, x, z), \bar{f}(t, x', z')) &\leq \lambda [D(x, x') + |z - z'|]; \end{aligned}$$

2. the limit (3.2) exists uniformly with respect to  $t, z \geq 0$  and  $x \in S$ ;
3. the functions  $\gamma(t), g(t)$  are uniformly continuous and  $0 \leq \gamma(t) \leq g(t) \leq t$ ;
4. the solution  $y(t)$  of equation (3.3),  $y(0) = x_0 \in S' \subset S$  belongs to the domain  $S$  together with a  $\rho$ -neighborhood for all  $t \geq 0$ .

Then for any  $\eta \in (0, \rho]$  and  $L > 0$  there exists  $\varepsilon^0(\eta, L) > 0$  such that for all  $\varepsilon \in (0, \varepsilon^0]$  and  $t \in [0, L\varepsilon^{-1}]$  the following estimate holds:

$$D(x(t), y(t)) \leq \eta, \quad (3.4)$$

where  $x(t), y(t)$  are solutions of equations (3.1) and (3.3) such that  $x(0) = y(0) = x_0$ .

*Proof.* According to Definition 2.7, the solutions of equations (3.1) and (3.3) are weakly continuous fuzzy mappings that satisfy the integral equations

$$\begin{aligned} x(t) &= x_0 + \varepsilon \int_0^t f \left( s, x(s), \max_{\tau \in [\gamma(s), g(s)]} |x(\tau)| \right) ds, \\ y(t) &= x_0 + \varepsilon \int_0^t \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds. \end{aligned}$$

Then

$$\begin{aligned} D(x(t), y(t)) &= D \left( x_0 + \varepsilon \int_0^t f \left( s, x(s), \max_{\tau \in [\gamma(s), g(s)]} |x(\tau)| \right) ds, \right. \\ &\quad \left. x_0 + \varepsilon \int_0^t \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds \right) \\ &= \varepsilon D \left( \int_0^t f \left( s, x(s), \max_{\tau \in [\gamma(s), g(s)]} |x(\tau)| \right) ds, \int_0^t \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds \right) \\ &\leq \varepsilon D \left( \int_0^t f \left( s, x(s), \max_{\tau \in [\gamma(s), g(s)]} |x(\tau)| \right) ds, \int_0^t f \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds \right) \\ &\quad + \varepsilon D \left( \int_0^t f \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds, \int_0^t \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds \right) \\ &\leq \varepsilon \lambda \int_0^t \left[ D(x(s), y(s)) + \left| \max_{\tau \in [\gamma(s), g(s)]} |x(\tau)| - \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right| \right] ds + \sigma(\varepsilon), \end{aligned}$$

where

$$\sigma(\varepsilon) = \max_{t \in [0, L\varepsilon^{-1}]} \beta(t, \varepsilon),$$

$$\beta(t, \varepsilon) = \varepsilon D \left( \int_0^t f \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds, \int_0^t \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds \right).$$

Let  $\delta(t) = \max_{s \in [0, t]} D(x(s), y(s))$ . As

$$\begin{aligned} & \left| \max_{\tau \in [\gamma(s), g(s)]} |x(\tau)| - \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right| \\ & \leq \max_{\tau \in [\gamma(s), g(s)]} ||x(\tau)| - |y(\tau)|| \leq \max_{\tau \in [\gamma(s), g(s)]} D(x(\tau), y(\tau)) \leq \delta(s), \end{aligned}$$

we have

$$\delta(t) \leq 2\lambda\varepsilon \int_0^t \delta(s) ds + \sigma(\varepsilon). \tag{3.5}$$

Divide the interval  $[0, L\varepsilon^{-1}]$  on the partial intervals with the points  $t_i = \frac{Li}{m\varepsilon}$ ,  $i = \overline{0, m}$ ,  $m \in \mathbb{N}$ . Let us estimate  $\beta(t, \varepsilon)$ , using the properties of the metric  $D$  for  $t \in [t_k, t_{k+1}]$ :

$$\begin{aligned} & \beta(t, \varepsilon) \\ & = \varepsilon D \left( \sum_{i=0}^{k-1} \int_{t_i}^{t_{i+1}} f \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds + \int_{t_k}^t f \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds, \right. \\ & \left. \sum_{i=0}^{k-1} \int_{t_i}^{t_{i+1}} \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds + \int_{t_k}^t \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds \right) \\ & \leq \varepsilon \left[ \sum_{i=0}^{k-1} D \left( \int_{t_i}^{t_{i+1}} f \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds, \int_{t_i}^{t_{i+1}} \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds \right) \right. \\ & \left. + D \left( \int_{t_k}^t f \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds, \int_{t_k}^t \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds \right) \right] \\ & \leq \varepsilon \sum_{i=0}^{k-1} \left[ \int_{t_i}^{t_{i+1}} D \left( f \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right), f \left( s, y(t_i), \max_{\tau \in [\gamma(t_i), g(t_i)]} |y(\tau)| \right) \right) ds \right] \end{aligned}$$

$$\begin{aligned}
& + \int_{t_i}^{t_{i+1}} D \left( \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right), \bar{f} \left( s, y(t_i), \max_{\tau \in [\gamma(t_i), g(t_i)]} |y(\tau)| \right) \right) ds \\
& + D \left( \int_{t_i}^{t_{i+1}} f \left( s, y(t_i), \max_{\tau \in [\gamma(t_i), g(t_i)]} |y(\tau)| \right) ds, \int_{t_i}^{t_{i+1}} \bar{f} \left( s, y(t_i), \max_{\tau \in [\gamma(t_i), g(t_i)]} |y(\tau)| \right) ds \right) \\
& + \varepsilon D \left( \int_{t_k}^t f \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds, \int_{t_k}^t \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds \right) \\
& \leq \varepsilon \sum_{i=0}^{k-1} \left[ 2\lambda \int_{t_i}^{t_{i+1}} \left[ D(y(s), y(t_i)) + \left| \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| - \max_{\tau \in [\gamma(t_i), g(t_i)]} |y(\tau)| \right| \right] ds \right. \\
& + D \left( \int_{t_i}^{t_{i+1}} f \left( s, y(t_i), \max_{\tau \in [\gamma(t_i), g(t_i)]} |y(\tau)| \right) ds, \int_{t_i}^{t_{i+1}} \bar{f} \left( s, y(t_i), \max_{\tau \in [\gamma(t_i), g(t_i)]} |y(\tau)| \right) ds \right) \\
& \left. + \varepsilon D \left( \int_{t_k}^t f \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds, \int_{t_k}^t \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds \right) \right]. \tag{3.6}
\end{aligned}$$

Let us estimate every summand in (3.6) separately:

$$\begin{aligned}
& \varepsilon \int_{t_i}^{t_{i+1}} D(y(s), y(t_i)) ds \\
& = \varepsilon \int_{t_i}^{t_{i+1}} D \left( y(t_i) + \varepsilon \int_{t_i}^s \bar{f} \left( \tau, y(\tau), \max_{\chi \in [\gamma(\tau), g(\tau)]} |y(\chi)| \right) d\tau, y(t_i) \right) ds \\
& = \varepsilon^2 \int_{t_i}^{t_{i+1}} D \left( \int_{t_i}^s \bar{f} \left( \tau, y(\tau), \max_{\chi \in [\gamma(\tau), g(\tau)]} |y(\chi)| \right) d\tau, \widehat{0} \right) ds \\
& \leq \varepsilon^2 \int_{t_i}^{t_{i+1}} \int_{t_i}^s D \left( \bar{f} \left( \tau, y(\tau), \max_{\chi \in [\gamma(\tau), g(\tau)]} |y(\chi)| \right), \widehat{0} \right) d\tau ds \\
& \leq \frac{\varepsilon^2 M}{2} \left( \frac{L}{\varepsilon m} \right)^2 = \frac{ML^2}{2m^2}. \tag{3.7}
\end{aligned}$$

Using the properties of the modulus of continuity

$$\omega(\psi, \sigma) = \sup\{|\psi(\tau_1) - \psi(\tau_2)|, |\tau_1 - \tau_2| < \sigma\}$$

of functions  $\gamma(t), g(t)$ , we get

$$\begin{aligned} & \varepsilon \int_{t_i}^{t_{i+1}} \left| \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| - \max_{\tau \in [\gamma(t_i), g(t_i)]} |y(\tau)| \right| ds \\ & \leq \varepsilon \int_{t_i}^{t_{i+1}} \varepsilon M \max \left\{ \omega \left( \gamma, \frac{L}{\varepsilon m} \right), \omega \left( g, \frac{L}{\varepsilon m} \right) \right\} ds \\ & = \frac{\varepsilon LM}{m} \max \left\{ \omega \left( \gamma, \frac{L}{\varepsilon m} \right), \omega \left( g, \frac{L}{\varepsilon m} \right) \right\} \\ & \leq \frac{\varepsilon LM}{m} \left( 1 + \frac{1}{\varepsilon m} \right) \max \{ \omega(\gamma, L), \omega(g, L) \}. \end{aligned} \tag{3.8}$$

From the uniform convergence to the average in (3.2) it follows that there exists a monotone decreasing function  $\Theta(t) \rightarrow 0$  as  $t \rightarrow \infty$  such that

$$\begin{aligned} & \varepsilon D \left( \int_{t_i}^{t_{i+1}} f \left( s, y(t_i), \max_{\tau \in [\gamma(t_i), g(t_i)]} |y(\tau)| \right) ds, \int_{t_i}^{t_{i+1}} \bar{f} \left( s, y(t_i), \max_{\tau \in [\gamma(t_i), g(t_i)]} |y(\tau)| \right) ds \right) \\ & \leq \frac{L}{m} \Theta \left( \frac{L}{\varepsilon m} \right). \end{aligned} \tag{3.9}$$

As the mappings  $f$  and  $\bar{f}$  are uniformly bounded by constant  $M$ , we have

$$\begin{aligned} & \varepsilon D \left( \int_{t_k}^t f \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds, \int_{t_k}^t \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) ds \right) \\ & \leq \varepsilon \int_{t_k}^t D \left( f \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right), \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right) \right) ds \\ & \leq \varepsilon \int_{t_k}^t D \left( f \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right), \hat{0} \right) ds \\ & \quad + \varepsilon \int_{t_k}^t D \left( \bar{f} \left( s, y(s), \max_{\tau \in [\gamma(s), g(s)]} |y(\tau)| \right), \hat{0} \right) ds \leq 2M\varepsilon \int_{t_k}^t ds = 2\frac{ML}{m}. \end{aligned} \tag{3.10}$$

Hence using (3.6)–(3.10), we have

$$\beta(t, \varepsilon) \leq \frac{\lambda ML^2}{m} + 2\lambda LM \left( \frac{1}{m} + \varepsilon \right) \max \{ \omega(\gamma, L), \omega(g, L) \}$$

$$+ \frac{2ML}{m} + L\Theta \left( \frac{L}{\varepsilon m} \right). \quad (3.11)$$

Let us choose  $m_0$  to satisfy the inequality

$$\frac{\lambda ML^2}{m_0} + \frac{2\lambda LM}{m_0} \max\{\omega(\gamma, L), \omega(g, L)\} + \frac{2ML}{m_0} < \frac{\eta}{2e^{2\lambda L}} \quad (3.12)$$

and then choose  $\varepsilon_0$  such that

$$2\lambda LM \max\{\omega(\gamma, L), \omega(g, L)\}\varepsilon + L\Theta \left( \frac{L}{\varepsilon m_0} \right) < \frac{\eta}{2e^{2\lambda L}}. \quad (3.13)$$

From (3.11)–(3.13) and (3.5) using the Gronwall–Bellman lemma, we get the statement of the theorem.  $\square$

*Remark 3.2.* From the definition of  $|x(t)|$  it follows that

$$|x(t)| = D(x(t), \hat{0}) = \sup_{\alpha \in [0,1]} h([x(t)]^\alpha, \{0\}) = h([x(t)]^0, \{0\}) = |[x(t)]^0|.$$

So the fuzzy differential equation (3.1) is equivalent to the following

$$x'(t) = \varepsilon f \left( t, x(t), \max_{\tau \in [\gamma(t), g(t)]} |[x(\tau)]^0| \right), \quad x(0) = x_0. \quad (3.14)$$

It is easy to show that instead of 0-level set of the fuzzy mapping  $x(t)$  any  $\alpha$ -level set,  $\alpha \in [0, 1]$ , can be taken. The substantiation of the averaging scheme will be almost the same.

## 4 Conclusion

In this paper the substantiation of one scheme of averaging for fuzzy differential equations with maxima is considered. These results generalize the results of [6] for differential equations with Hukuhara derivative with maxima.

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