

## On Some Stochastic Fractional Integro-Differential Equations

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### Abstract

Some classes of stochastic fractional integro-partial differential equations are investigated. Mild solutions of the nonlocal Cauchy problem for the considered classes are studied. The Leray–Schauder principle is used to establish the existence of stochastic solutions. The uniqueness of the solution of the considered problem is also studied under suitable conditions.

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### 1. Introduction

Many physical models are represented by semi-linear stochastic fractional integro-partial differential systems of the form

$$\frac{\partial^\alpha u(x, t)}{\partial t^\alpha} = L(x, D)u(x, t) + f(u(x, t)) + \int_0^t g(u(x, s))dW(s), \quad (1.1)$$

with the nonlocal condition

$$u(x, 0) = \varphi(x) + \sum_{i=1}^p c_i u(x, t_i), \quad (1.2)$$

where  $0 < \alpha \leq 1$ ,  $0 \leq t_1 < t_2 < \dots < t_p$ ,  $x$  is an element of the  $n$ -dimensional Euclidean space  $\mathbb{R}^n$ ,  $D = (D_1, \dots, D_n)$ ,  $D_i = \frac{\partial}{\partial x_i}$ ,  $i = 1, \dots, n$ ,  $W(t)$  is a standard

Brownian motion defined over the filtered probability space  $(\Omega, F, F_t, P)$ ,  $u \in \mathbb{R}^k$  and  $\{F_t : 0 \leq t \leq T\}$  is a right-continuous, increasing family of sub  $\sigma$ -algebras of  $F$ .

Let  $H$  be the space of all  $k$ -dimensional vectors of functions defined on  $\mathbb{R}^n$  such that

$$\int_{\mathbb{R}^n} \sum_{i=1}^k u_i^2(x) dx < \infty, \quad u = (u_1, \dots, u_k).$$

A scalar product  $(u, v)$  in  $H$  is defined by

$$(u, v)_H = \sum_{i=1}^k \int_{\mathbb{R}^n} u_i(x) v_i(x) dx.$$

If  $S = \{V(x, t, \omega) : \Omega \rightarrow H | 0 \leq t \leq T\}$  is a stochastic process, then we shall write for simplicity  $V(x, t)$  and  $V_t : [0, T] \rightarrow H$  in place of  $S$ .

The collection of all strongly measurable  $H$ -valued random variables denoted by  $L^2(\Omega, H)$  is a Banach space equipped with the norm

$$\|V_t\|_{L^2(\Omega, H)} = [E \|V_t(\omega)\|_H^2]^{\frac{1}{2}}, \quad E(g) = \int_{\Omega} g(\omega) dP,$$

where  $E(g)$  is the expectation of  $g$ . It is assumed that

$$L(x, D) = L_0(x, D) + L_1(x, D),$$

where

$$L_0(x, D) = \sum_{|q|=2m} A_q(x) D^q, \quad L_1(x, D) = \sum_{|q|<2m} A_q(x) D^q,$$

$D^q = D_1^{q_1} \dots D_n^{q_n}$ ,  $q = (q_1, \dots, q_n)$  is a multi index,  $|q| = q_1 + \dots + q_n$ , and  $\{A_q(x) : |q| \leq 2m\}$  is a family of deterministic square matrices of order  $k$ . Following Petrovsky it is assumed that

$$\det\{(-1)^m L_0(x, \sigma) - \lambda I\} = 0$$

has roots which satisfy the inequality  $\text{Re} \lambda < -\delta$ ,  $\delta > 0$  for all  $x \in \mathbb{R}^n$ ,  $t \geq 0$  and for any real vector  $\sigma$ ,  $\sigma_1^2 + \dots + \sigma_n^2 = 1$ , [2]. If  $B$  is a matrix of order  $m \times n$ , then we introduce  $|B|$  by

$$|B| = \sum_{i,j} |b_{ij}|.$$

It is assumed that the coefficients of  $L(x, D)$  are bounded on  $\mathbb{R}^n$  and satisfy the Hölder condition (with exponent  $\gamma \in (0, 1]$ ). It is well known that there exists a fundamental matrix solution  $Z(x, y, t)$ , which satisfies the system

$$\frac{\partial Z(x, y, t)}{\partial t} = L(x, D) Z(x, y, t), \quad t > 0, x, y \in \mathbb{R}^n.$$

This fundamental matrix satisfies the inequality

$$\begin{aligned}
 |D^q Z(x, y, t)| &\leq K_1 t^{-\rho_1} \exp(-K_2 \rho_2), \\
 |q| \leq 2m, \rho_1 &= -\frac{n + |q|}{2m}, \rho_2 = \sum_{i=1}^n |x_i - y_i|^\lambda t^{-\frac{1}{2m-1}}, \\
 \lambda &= \frac{2m}{2m-1}, \quad (K_1 > 0 \text{ and } K_2 > 0 \text{ are constants}).
 \end{aligned}
 \tag{1.3}$$

The set  $\{v_t \in C([0, T]; L^2(\Omega, H)) : v_t \text{ is } F_t \text{ adapted}\}$  is denoted by  $C([0, T]; H)$ , where  $C([0, T]; H)$  denotes the space of  $k$ -dimensional vectors of continuous functions from  $[0, T]$  into  $H$  equipped with norm

$$\|v\|_C = \sup_{t \in [0, T]} [E \|v_t\|_H^2]^{\frac{1}{2}}.$$

The purpose of this paper is to study the mild solutions of the nonlocal Cauchy problem (1.1), (1.2), assuming that  $\varphi$  is an  $F_0$ -measurable  $H$ -valued stochastic process. The results in this note may be regarded as a generalization of some recent results developed in [3–11, 14, 16, 17].

In Section 2, we shall find the mild solutions of the nonlocal Cauchy problem (1.1), (1.2).

The nonlocal Cauchy problem (1.1), (1.2) has applications in many fields such as viscoelasticity and electromagnetic theory, [1, 12, 13, 15, 18].

## 2. Stochastic Integral Equation

A slightly modified version of the nonlocal Cauchy problem (1.1), (1.2) is considered. Using the definitions of the fractional derivatives and integrals, it is suitable to rewrite the considered problem in the form

$$\begin{aligned}
 u(x, t) &= u(x, 0) + \frac{1}{\Gamma(\alpha)} \int_0^t (t - \theta)^{\alpha-1} L(x, D)u(x, \theta) d\theta \\
 &\quad + \frac{1}{\Gamma(\alpha)} \int_0^t (t - \theta)^{\alpha-1} f(u(x, \theta)) d\theta \\
 &\quad + \frac{1}{\Gamma(\alpha)} \int_0^t \int_0^\theta (t - \theta)^{\alpha-1} g(u(x, s)) dW(s) d\theta.
 \end{aligned}
 \tag{2.1}$$

Let  $Z(t)$  be the operator defined on  $H$ , for every  $t > 0$ , by

$$Z(t)\varphi = \int_{\mathbb{R}^n} Z(x, y, t)\varphi(y) dy.$$

According to condition (1.3), there is a positive constant  $M$  such that

$$\|Z(t)\|_H \leq M.
 \tag{2.2}$$

Let us consider the integrals of the operator-valued functions

$$\begin{aligned}\psi(t) &= \int_0^\infty \xi_\alpha(\theta) Z(t^\alpha \theta) d\theta, \\ \psi^*(t) &= \alpha \int_0^\infty \theta t^{\alpha-1} \xi_\alpha(\theta) Z(t^\alpha \theta) d\theta,\end{aligned}$$

where  $\xi_\alpha(\theta)$  is a probability density function defined on  $[0, \infty]$  (see [3]). It is supposed that

$$cM < 1, \quad \text{where } c = \sum_{i=1}^p |c_i|. \quad (2.3)$$

**Theorem 2.1.** If  $u \in C([0, T]; H)$  is an  $F_t$ -adapted stochastic process that satisfies equation (2.1) a.s.  $[p]$ , then  $u$  satisfies the equation (a.s.  $[p]$ )

$$\begin{aligned}u(x, t) &= (\psi(t)\Lambda^{-1}\varphi)(x) \\ &+ \psi(t)\Lambda^{-1} \sum_{i=1}^p c_i \int_0^{t_i} (\psi^*(t_i - \eta)f(u))(x, \eta) d\eta \\ &+ \psi(t)\Lambda^{-1} \sum_{i=1}^p c_i \int_0^{t_i} \int_0^\eta (\psi^*(t_i - \eta)g(u))(x, s) dW(s) d\eta \\ &+ \int_0^t (\psi^*(t - \eta)f(u))(x, \eta) d\eta \\ &+ \int_0^t \int_0^\eta (\psi^*(t - \eta)g(u))(x, s) dW(s) d\eta,\end{aligned} \quad (2.4)$$

where  $\Lambda = I - \sum_{i=1}^p c_i \psi(t_i)$ ,  $I$  is the identity operator.

*Proof.* Using (2.2) and (2.3), we find that the inverse operator  $\Lambda^{-1}$  exists. Using the results in [3], the solution of equation (2.1) can be written in the form (a.s.  $[p]$ )

$$\begin{aligned}u(x, t) &= \int_0^\infty \int_{\mathbb{R}^n} Z(x, y, t^\alpha \theta) \xi_\alpha(\theta) u(y, 0) dy d\theta \\ &+ \alpha \int_0^t \int_0^\infty \int_{\mathbb{R}^n} \theta (t - \eta)^{\alpha-1} \xi_\alpha(\theta) Z(x, y, (t - \eta)^\alpha \theta) f(u(y, \eta)) dy d\theta d\eta \\ &+ \alpha \int_0^t \int_0^\infty \int_{\mathbb{R}^n} \theta (t - \eta)^{\alpha-1} \xi_\alpha(\theta) Z(x, y, (t - \eta)^\alpha \theta) \\ &\times \int_0^\eta g(u(y, s)) dW(s) dy d\theta d\eta.\end{aligned}$$

It is easy to see that (a.s. [p])

$$\begin{aligned}
 \sum_{i=1}^p c_i u(x, t_i) &= \left( \Lambda^{-1} \sum_{i=1}^p c_i \psi(t_i) \varphi \right) (x) \\
 &+ \Lambda^{-1} \sum_{i=1}^p \left( c_i \int_0^{t_i} \psi^*(t_i - \eta) f(u) \right) (x, \eta) d\eta \\
 &+ \Lambda^{-1} \sum_{i=1}^p \left( c_i \int_0^{t_i} \int_0^\eta \psi^*(t_i - \eta) g(u) \right) (x, s) dW(s) d\eta. \quad (2.5)
 \end{aligned}$$

Using (1.2) and (2.5), one gets (a.s. [p])

$$\begin{aligned}
 (\psi(t)\varphi)(x) + \left( \psi(t) \sum_{i=1}^p c_i u \right) (x_i, t_i) &= (\psi(t)\Lambda^{-1}\varphi)(x) \\
 &+ \psi(t)\Lambda^{-1} \sum_{i=1}^p c_i \int_0^{t_i} (\psi^*(t_i - \eta) f(u))(x, \eta) d\eta \\
 &+ \psi(t)\Lambda^{-1} \sum_{i=1}^p c_i \int_0^{t_i} \int_0^\eta (\psi^*(t_i - \eta) g(u))(x, s) dW(s) d\eta.
 \end{aligned}$$

Hence the required result follows. ■

Now we define a mild solution of equation (2.1) to be an  $F_t$ - adapted stochastic process  $u \in ([0, T]; H)$  which satisfies equation (2.4), a.s. [p].

**Theorem 2.2.** If  $\|f\|_C + \|g\|_C \leq K$  for all  $u \in S_\gamma = \{u \in C([0, T]; H) \mid \|u\|_C \leq \gamma\}$  and if

$$ME(\|\Lambda^{-1}\varphi\|_H) + KM^2T^\alpha \|\Lambda^{-1}\|_H + KMT^\alpha + MKT^{1+\alpha} + KM^2T^{1+\alpha} \leq \gamma, \quad (2.6)$$

where  $K$  and  $\gamma$  are positive constants, then there exists a mild solution of equation (2.1), a.s. [p].

*Proof.* Let  $Q$  be a map defined on  $S_\gamma$  by

$$\begin{aligned}
 (Qu)(x, t) &= (\psi(t)\Lambda^{-1}\varphi)(x) \\
 &+ \psi(t)\Lambda^{-1} \sum_{i=1}^p c_i \int_0^{t_i} (\psi^*(t_i - \eta) f(u))(x, \eta) d\eta \\
 &+ \psi(t)\Lambda^{-1} \sum_{i=1}^p c_i \int_0^{t_i} \int_0^\eta (\psi^*(t_i - \eta) g(u))(x, s) dW(s) d\eta \\
 &+ \int_0^t (\psi^*(t - \eta) f(u))(x, \eta) d\eta + \int_0^t \int_0^\eta (\psi^*(t - \eta) g(u))(x, s) dW(s) d\eta.
 \end{aligned}$$

Using (2.6) and noting that  $\int_0^\infty \theta \xi_\alpha(\theta) d\theta = 1$ , one gets,

$$E(\|Qu_t\|_H) \leq \gamma,$$

where

$$\|v_t\|_H^2 = \int_{\mathbb{R}^n} \sum_{i=1}^k v_i^2(x, t) dx.$$

Thus  $Q$  maps  $C([0, T]; H)$  into itself. For  $0 \leq t_1 < t_2 \leq T$ , we have

$$\begin{aligned} & E \|Qu_{t_1} - Qu_{t_2}\|_H \\ & \leq [E(\|\Lambda^{-1}\varphi\|_H) + 2cKT^\alpha \|\Lambda^{-1}\|_H] \|\psi(t_1) - \psi(t_2)\|_H \\ & \quad + 2K \int_{t_1}^{t_2} \|\psi^*(t - \eta)\|_H d\eta + 2M \int_0^{t_1} \|\psi^*(t_1 - \eta) - \psi^*(t_2 - \eta)\|_H d\eta. \end{aligned} \quad (2.7)$$

It can be proved that

$$\|[\psi(t_2) - \psi(t_1)]w\|_H \leq \alpha M [\log t_2 - \log t_1] \|w\|_H. \quad (2.8)$$

Consequently  $\|\psi(t_2) - \psi(t_1)\|_H$  tends to zero as  $s$  tends to  $t$ . Similarly

$$\lim_{t_1 \rightarrow t_2} \int_0^{t_1} \|\psi^*(t_2 - \eta) - \psi^*(t_1 - \eta)\|_H d\eta = 0, \quad (2.9)$$

$$\lim_{t_1 \rightarrow t_2} \int_{t_1}^{t_2} \|\psi^*(t - \eta)\|_H d\eta = 0, \quad (\text{see [7]}). \quad (2.10)$$

The right-hand side of inequality (2.7) is independent of  $u$  and by using (2.8), (2.9) and (2.10), one gets that  $\|Qu_{t_1} - Qu_{t_2}\|_H$  tends to zero as  $t_1 \rightarrow t_2$ . Now it is clear that by Arzela–Ascoli’s theorem,  $\{(Qu)(x, t) : u \in C([0, T]; H)\}$  is precompact. Hence by Leray–Schauder’s fixed point theorem,  $Q$  has a fixed point in  $C([0, T]; H)$  and any fixed point of  $Q$  represents a mild solution of equation (2.1), a.s.  $[p]$ . This completes the proof of the theorem.  $\blacksquare$

**Theorem 2.3.** Suppose the Lipschitz condition

$$E[\|f(u) - f(v)\|_H] + E[\|g(u) - g(v)\|_H] \leq K_1 E(\|u - v\|_H)$$

is satisfied, where  $K_1 > 0$  is a constant. If Equation (2.1) has a mild solution  $u \in C([0, T]; H)$ , then that mild solution is unique on  $[0, T]$ .

*Proof.* For  $u, v, \in C([0, T]; H)$  we infer from (2.4) that

$$\begin{aligned}
 E \|u_t - v_t\|_H^2 &\leq \frac{K_2 T^\alpha}{\alpha} \int_0^t (t - \eta)^{\alpha-1} E \|u_\eta - v_\eta\|_H^2 d\eta \\
 &\quad + \frac{K_3 T^\alpha}{\alpha} \sum_{i=1}^p |c_i| \int_0^{t_i} (t_i - \eta)^{\alpha-1} E \|u_\eta - v_\eta\|_H^2 d\eta \\
 &\quad + K_2 \int_0^t (t - s)^\alpha E \|u_s - v_s\|_H^2 ds \\
 &\quad + K_3 \sum_{i=1}^p |c_i| \int_0^{t_i} (t_i - s)^\alpha E \|u_s - v_s\|_H^2 ds. \tag{2.11}
 \end{aligned}$$

Let  $\rho(u, v) = \sup_{t \in [0, T]} (e^{-\lambda t} E \|u_t - v_t\|_H^2)$ , where  $\lambda > 1$ . It is easy to see that

$$\begin{aligned}
 &\int_0^{t_i} (t_i - \eta)^{\alpha-1} E \|u_\eta - v_\eta\|_H^2 d\eta \\
 &\leq \left[ \lambda^{1-\alpha} \int_0^{t_i - \frac{1}{\lambda}} d\eta \right] \rho(u, v) \\
 &\leq e^{\lambda t_i} \left( 1 + \frac{1}{\alpha} \right) \left( \frac{1}{\lambda} \right)^\alpha \rho(u, v). \tag{2.12}
 \end{aligned}$$

Let us consider the following two cases. The first one is  $t \geq t_p$  and the second is  $t \leq t_p$ . For the first case  $t \geq t_p$ , we deduce from (2.11) and (2.12) that

$$e^{-\lambda t} E \|u_t - v_t\|_H^2 \leq K_4 \left[ \left( 1 + \frac{1}{\lambda} \right)^\alpha + \frac{1}{\lambda} \right] \rho(u, v).$$

Thus  $\rho(u, v) = 0$ , for sufficiently large  $\lambda$ , ( $K_4 > 0$  is a constant). For the second case  $t \leq t_p$ , one gets

$$E \|u_t - v_t\|_H^2 \leq K_5 t_p^\alpha \sup_{t \in [0, T]} E \|u_t - v_t\|_H^2, \quad (K_5 > 0 \text{ is a constant}).$$

Now if  $t_p$  is sufficiently small such that  $K_5 t_p^\alpha < 1$ , we get

$$\sup E \|u_t - v_t\|_H^2 = 0.$$

This completes the proof of the theorem. ■

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